

Claims

WHAT IS CLAIMED:

5 1. A system comprising:

an engine having a first and second group of
cylinders;

a sensor coupled to at least one of said first and
second groups; and

10 a controller for operating the engine in a first mode
with a mixture of air and substantially no injected fuel in
the first combustion group and with air and injected fuel
in the second combustion group, operating in second mode
where both of said first and second groups combusts a
15 mixture of air and injected fuel, and disabling adaptive
learning of the sensor during said first mode and enabling
said adaptive learning during the second mode.

2. The system recited in Claim 1 wherein said adaptive
20 learning comprises calculating a correction value for said
sensor; and when in said first mode, the second combustion
group operates with a lean air-fuel ratio.

3. The system recited in Claim 2 wherein said sensor is
25 an exhaust gas oxygen sensor.

4. The system recited in Claim 3 wherein said first and
second cylinder groups have an equal number of cylinders.

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5. A method for operating an engine having a first and second group of cylinders, comprising:

operating in a first mode with the first cylinder group operating with air and substantially no injected fuel and the second cylinder group operating by combusting air and fuel, providing a request for enabling adaptive learning of a sensor coupled to the engine; and

in response to said request, disabling said first mode of operation and operating the engine in a second mode of operation.

6. The method recited in claim 5, wherein said second mode of operation comprises operating both first and second cylinder groups with a combusted air-fuel mixture.

7. The method recited in Claim 6 wherein said combusted air-fuel mixture of said second mode is substantially near stoichiometry.

8. The method recited in Claim 5 wherein said sensor is coupled to an engine exhaust.

9. The method recited in Claim 5 wherein said sensor is an exhaust air-fuel ratio sensor.

10. The method recited in Claim 5 wherein said adaptive learning corrects for sensor errors.